

ROBotic Open-architecture Technology for Cognition, Understanding, and Behavior



Project No. 004370

RobotCub

Development of a Cognitive Humanoid Cub

Instrument: Integrated Project

Thematic Priority: IST - Cognitive Systems

D5.7

Software implementation for the iCub & integration in the iCub Cognitive Architecture.

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Responsible Person: Aude Billard

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Dissemination Level			
PU	Public	PU	
PP	Restricted to other programme participants (including the Commission Service)		
RE	Restricted to a group specified by the consortium (including the Commission Service)		
CO	Confidential, only for members of the consortium (including the Commission Service)		



Software Implementation of the iCub Cognitive Architecture

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Introduction

This deliverable item is the implementation of the imitation behaviours as described in the previous Deliverables 5.1-5.6 into the iCub and in particular the integration of this software in the Cognitive Architecture.

iCub cognitive architecture version 1.0

The iCub cognitive architecture manual is available from: http://eris.liralab.it/iCub/dox/html/group icub applications.html

Each application listed at this documentation page is built following the iCub standards and include:

- A set of Yarp modules, each with specific documentation that can be found at: http://eris.liralab.it/iCub/dox/html/group icub module.html
- A set of scripts (bash) that can instantiate, terminate, and control the behaviour realized by the set of modules
- Further documentation, paper references, class documentation, etc.

Entry point 3

This document is only a placeholder. The actual deliverable is the software and its documentation.

Videos of the experiments running on the iCub are available from: http://eris.liralab.it/wiki/Deliverable_2.2

and, in particular, scroll the page down to the section titled "Affordances" and "Body schema". Papers describing the experiment are available for download.

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