



ROBotic Open-architecture Technology for
Cognition, Understanding, and Behavior



Project No. 004370

RobotCub

Development of a Cognitive Humanoid Cub

Instrument: Integrated Project
Thematic Priority: IST – Cognitive Systems

**D3.1 Initial implementation of models of sensorimotor
coordination primitives
Addendum (videos)**

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Dissemination Level		
PU	Public	PU
PP	Restricted to other programme participants (including the Commission Service)	
RE	Restricted to a group specified by the consortium (including the Commission Service)	
CO	Confidential, only for members of the consortium (including the Commission Service)	



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1 Introduction

This deliverable consists of a report and demo(s). The demonstrations are provided both at the review meeting and in form of videos of the various experiments. This deliverable item is linked also to D3.6 which includes the software required to run the demonstrations on the iCub robot.

2 Links

The main link to the videos and references about the experiments described in the D3.1 main text is: http://eris.liralab.it/wiki/Deliverable_3.1