



ROBotic Open-architecture Technology for
Cognition, Understanding, and Behavior



Project No. 004370

RobotCub

Development of a Cognitive Humanoid Cub

Instrument: Integrated Project
Thematic Priority: IST – Cognitive Systems

**D3.6 Software implementation of the phylogenetic abilities
specifically for the iCub & integration in the iCub
Cognitive Architecture**

Due Date: Month 65
Submission date: Month 65

Start date of project: **01/09/2004**

Duration: **65 months**

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Revision: **2.0**

Project co-funded by the European Commission within the Sixth Framework Programme (2002-2006)		
Dissemination Level		
PU	Public	PU
PP	Restricted to other programme participants (including the Commission Service)	
RE	Restricted to a group specified by the consortium (including the Commission Service)	
CO	Confidential, only for members of the consortium (including the Commission Service)	



Table of Contents

1	Introduction.....	3
2	Links	3



1 Introduction

This deliverable is the software that implements the models of sensorimotor coordination studied in the Workpackage 3. Beside the software per se that can be accessed on the iCub SourceForge SVN repository, we are including a wiki page with videos, papers and links to the iCub application or modules that implement a specific behaviour. This deliverable item is linked also to D3.1 which a description of various experiments on sensorimotor coordination on the iCub, in infants and in adult humans.

2 Links

The main link to the videos and references about the experiments described in the D3.1 and relevant to D3.6 can be browsed at the following URL:

http://eris.liralab.it/wiki/Deliverable_3.6_update