

Open Call

RobotCub launched an Open Call for proposals. As a result six robots were given (or will be delivered) free of charge to research institutions or small consortia worldwide. The first robots are already out. This page only reports a few details about the Open Call and provides the list of the winners. The [RobotCub Wiki contains a link a community page](#) where we share experiences about the iCub.

The Open Call invited proposals for projects which focus on using the humanoid robot iCub for embodied artificial cognitive systems research. An iCub kit was awarded to each of the applicants who submitted the six best proposals. Here is the list of the winners.

Institution	Project title	Investigators
Dept. of Computing/Dept. of Electrical Engineering, Imperial College, London	Embodied cognition using internal simulation and a global workspace	Murray Shanahan, Yiannis Demiris
Institute for Intelligent Systems and Robotics. Universite' Pierre et Marie Curie - Paris	Motor, Affective and Cognitive Scaffolding for iCub (MACSi)	Philippe Bidaud, Olivier Sigaud, Vincent Padois
Human and Robot Cognitive Systems Group, INSERM U 846 Stem Cell and Brain Research Institute, Lyon	Development of Shared InTentions and Cooperation in a Humanoid Robot via Situated SIMulation Models (SitSim)	Peter Ford Dominey
KOVAN Research Lab, Middle East Technical University (METU)	Emergence of Communication in iCub through Sensorimotor and Social Interaction	Erol Sahin
Image Understanding and Knowledge Based Systems, Technische Universit•at M•unchen, Munich	iCubKidManS: iCub development of Kids' Manipulation Skills	Michael Beetz, Alexis Maldonado, Federico Ruiz
Institute of Audiovisual Studies, Universitat Pompeu Fabra, Barcelona	DAC-iCub: An integrated anthropomorphic neuromorphic cognitive architecture for the iCub	Paul Verschure